

3. The electronic device of claim 1, further comprising a touch sensitive interface, the one or more processors to cause the one or more thermal elements to terminate application of the heat to the shape memory polymer upon detecting, with the touch sensitive interface, an object proximately located with the fascia.

4. The electronic device of claim 1, further comprising a user interface, the one or more processors to present indicia on the user interface when the one or more thermal elements selectively apply the heat to the shape memory polymer, the indicia indicating that the heat is being applied to the shape memory polymer.

5. The electronic device of claim 1, further comprising a power interface to receive energy from a source coupled to the power interface, the one or more processors to cause the one or more thermal elements to selectively apply the heat to the shape memory polymer only after the source is coupled to the power interface.

6. The electronic device of claim 1, the one or more processors to cause the one or more thermal elements to selectively apply the heat to the shape memory polymer when the electronic device is in a low power or sleep mode.

7. The electronic device of claim 1, the one or more processors to cause the one or more thermal elements to selectively apply the heat to the shape memory polymer in accordance with a varying duty cycle.

8. The electronic device of claim 1, an amount of heat applied by the one or more thermal elements a function of thermal element density.

9. The electronic device of claim 1, the deformation comprising one or more of:

- scratches along the fascia;
- breakage of the fascia; or
- bending of the fascia.

10. The electronic device of claim 1, the one or more thermal elements to selectively apply the heat by an amount sufficient to cause the shape memory polymer to exceed a predefined transition temperature for at least a predefined duration along the at least a portion of the fascia.

11. The electronic device of claim 10, the one or more thermal elements comprising a matrix of optically transparent resistive electrodes.

12. The electronic device of claim 11, one or more optically transparent resistive electrodes having an impedance of between 200 and 1000 ohms, inclusive.

13. The electronic device of claim 11, further comprising a pellucid substrate disposed adjacent to the fascia, the matrix of optically transparent resistive electrodes disposed along the pellucid substrate.

14. The electronic device of claim 11, the matrix of optically transparent resistive electrodes comprising an interlaced matrix of optically transparent resistive electrodes.

15. The electronic device of claim 10, the one or more thermal elements comprising a capacitive touch-sensitive film.

16. The electronic device of claim 1, further comprising a companion attachment configured to selectively couple to the electronic device, the companion attachment comprising the one or more thermal elements.

17. A method, in an electronic device, comprising:

detecting, with one or more processors of the electronic device, a deformation along a portion of a fascia of the electronic device, the fascia comprising a shape memory polymer; and

selectively applying heat, with one or more thermal elements disposed along the fascia and operable with the one or more processors, to the portion to at least partially repair the deformation of the fascia.

18. The method of claim 17, further comprising receiving, from a touch sensitive user interface operable with the one or more processors, user input demarcating the portion.

19. The method of claim 18, further comprising presenting, on the touch sensitive user interface, indicia indicating the selectively applying the heat by the one or more thermal elements is occurring.

20. The method of claim 17, further comprising terminating the selectively applying upon detecting an object proximately located with the fascia.

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